



... [1] ... [1] ... « - ».

... [1] ... [1] ... j t ... [1]

... k, ... [1] ... :  $\eta_{ij} = 1/D_{ij}$ ,  $D_{ij}$  ...

« j, » ... [1] ... (-j) « , » ...  $\tau_{ij}(t)$ .

$$\begin{cases} P_{ij}^k(t) = \frac{[\tau_{ij}]^\alpha \cdot [\eta_{ij}]^\beta}{\sum_{j \in J_i^k} [\tau_{ij}]^\alpha \cdot [\eta_{ij}]^\beta}, & j \in J_i^k \\ P_{ij}^k(t) = 0, & j \notin J_i^k \end{cases} \quad (1)$$

$\alpha$   $\beta$  -  $\alpha = 0$ ,  $\beta = 0$ ,

"  $\emptyset$  - , 2012. 9 : , , " . [1]

k (-j)

$$\Delta\tau_{ij}^k(t) = \begin{cases} \frac{Q}{L^k(t)}, & (i, j) \in T^k(t) \\ 0, & (i, j) \notin T^k(t) \end{cases}$$

$T^k(t)$  - , k ;  $L^k(t)$   $\hat{\delta}$  ; Q  $\hat{\delta}$  . [1]

$\hat{\delta}$

$\in [0,1]$ .

$$\tau_{ij}(t+1) \leftarrow (1-p)\tau_{ij}(t) + \Delta\tau_{ij}(t), \quad (2)$$

$$\Delta\tau_{ij}(t) = \sum_{k=1}^m \tau_{ij}^k(t); \quad m -$$

$\tau_0$  .

$\hat{\delta}$  . [1]

L+  $\hat{\delta}$  , +, +, Q/L+, +

+  $e$  +,  $eQ/L$  +,

(Rank-Based Ant Systems),

(Ant Colony Systems),

( - IN

Ant Systems).

. [1]

$\hat{\delta}$

. [1]

2- t, 3- t -

. [1]

( « »)

.

**Ant-Q** . [3]

1995

Q-learning.

. Ant-Q

Q-  
« Q- »

**Ant Colony System** . [3]  
1997

**Max-min Ant System** . [3]

**ASrank** . [3]

. [3]

main ().

$\alpha, \beta, Q, \tau_0$

4,5,6í 17.

( . 1).

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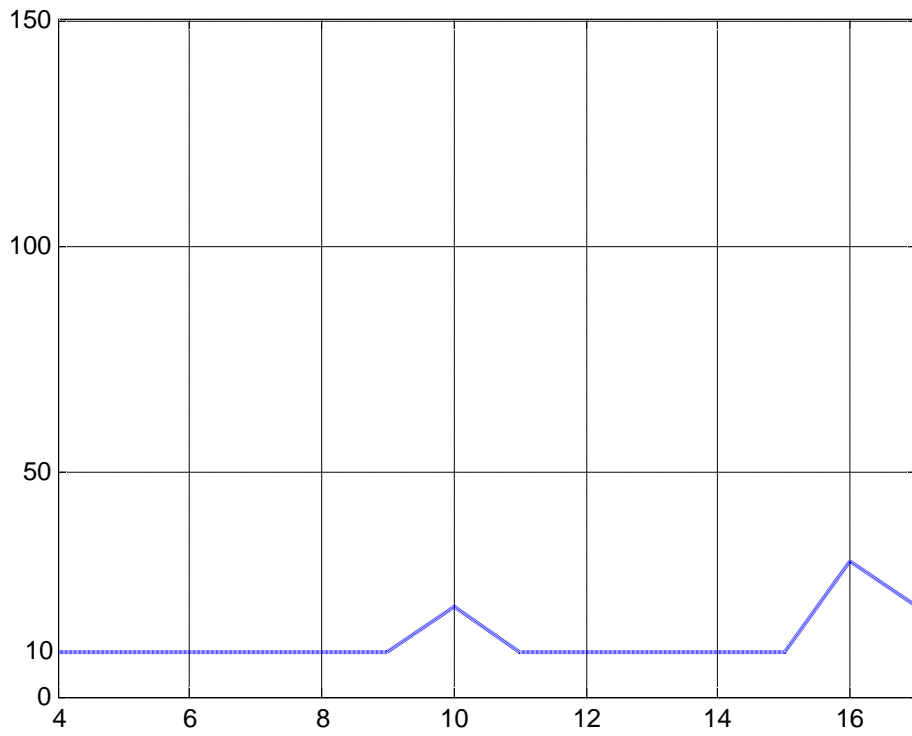
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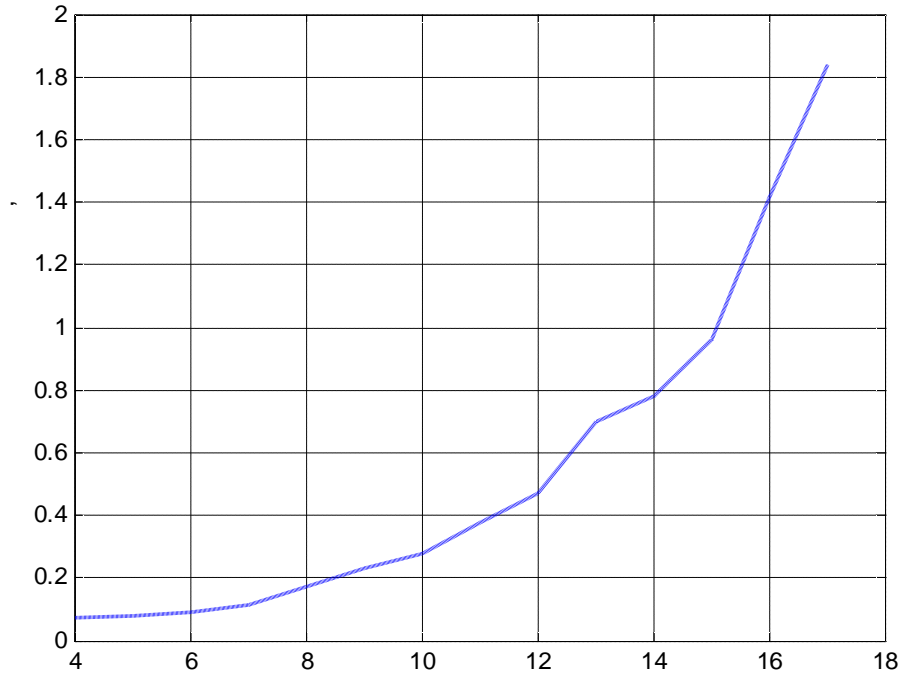
10.

$\alpha, \beta, Q, \tau_0$ .

( . 2).



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. 2.

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2. . . / . . , . . //
3. . . [ . . ] . ó : URL:

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